



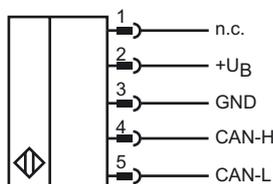
Model number

INY030D-F99-B16-V15

Features

- E1-Type approval
- High shock resistance
- Extended temperature range -40 ... +85 °C
- CANopen interface
- Measuring range -15° ... +15°
- Increased noise immunity 100 V/m

Electrical connection



Technical Data

General specifications

| | |
|-----------------------|----------------------------|
| Type | Inclination sensor, 2-axis |
| Measurement range | -15 ... 15 ° |
| Absolute accuracy | ≤ ± 0.2 ° |
| Response delay | ≤ 25 ms |
| Resolution | ≤ 0.01 ° |
| Repeat accuracy | ≤ ± 0.02 ° |
| Temperature influence | ≤ 0.004 °/K |

Functional safety related parameters

| | |
|--------------------------------|-------|
| MTTF _d | 300 a |
| Mission Time (T _M) | 20 a |
| Diagnostic Coverage (DC) | 0 % |

Indicators/operating means

| | |
|---------------------|------------|
| Operation indicator | LED, green |
|---------------------|------------|

Electrical specifications

| | |
|---|----------------|
| Operating voltage U _B | 10 ... 30 V DC |
| No-load supply current I ₀ | ≤ 50 mA |
| Time delay before availability t _v | ≤ 2.5 s |

Interface

| | |
|------------------|-----------------------------------|
| Interface type | CANopen |
| Device profile | CiA410, Ver. 1.2 |
| Data output code | binary code |
| Transfer rate | 10 ... 1000 kBit/s , programmable |
| Node ID | 1 ... 127 , programmable |
| Termination | external |
| Cycle time | ≥ 20 ms |

Ambient conditions

| | |
|---------------------|--------------------------------|
| Ambient temperature | -40 ... 85 °C (-40 ... 185 °F) |
| Storage temperature | -40 ... 85 °C (-40 ... 185 °F) |

Mechanical specifications

| | |
|----------------------|--------------------------|
| Connection type | 5-pin, M12 x 1 connector |
| Housing material | PA |
| Degree of protection | IP68 / IP69K |
| Mass | 240 g |

Factory settings

| | |
|---------------|------------|
| Node ID | 1 |
| Transfer rate | 250 kBit/s |

Compliance with standards and directives

| | |
|-----------------------------|---|
| Standard conformity | |
| Shock and impact resistance | 100 g according to DIN EN 60068-2-27 |
| Standards | EN 60947-5-2:2007 IEC 60947-5-2:2007 |

Approvals and certificates

| | |
|------------------|--|
| UL approval | cULus Listed, Class 2 Power Source |
| CSA approval | cCSAus Listed, General Purpose, Class 2 Power Source |
| E1 Type approval | 10R-04 |

EMC Properties

Interference immunity in accordance with
DIN ISO 11452-2: 100 V/m

Frequency band 20 MHz up to 2 GHz

Mains-borne interference in accordance with ISO 7637-2:

| | 1 | 2a | 2b | 3a | 3b | 4 |
|-------------------|-----|-----|-----|-----|-----|-----|
| Severity level | III | III | III | III | III | III |
| Failure criterion | C | A | C | A | A | C |

EN 61000-4-2: CD: 8 kV / AD: 15 kV

Severity level IV IV

EN 61000-4-3: 30 V/m (80...2500 MHz)

Severity level IV

EN 61000-4-4: 2 kV

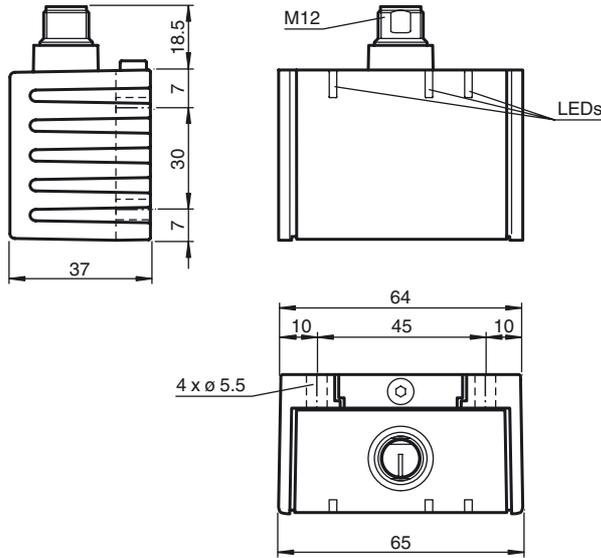
Severity level III

EN 61000-4-6: 10 V (0.01...80 MHz)

Severity level III

EN 55011: Klasse A

Dimensions



Sensor Orientation

In the default setting the zero position of the sensor is reached, when the sensor is mounted on a horizontal plane and electrical connection faces sideways.

Mounting of the sensor

Sensors from the -F99 series consist of a sensor module and accompanying cast aluminum housing. Select a horizontal flat surface with minimum dimensions of 70 mm x 50 mm to mount the sensor. Mount the sensor as follows:



1. Loosen the central screw under the sensor connection.
 2. Slide back the clamping element until you are able to remove the sensor module from the housing.
 3. Remove the sensor module from the housing
 4. Position the housing at the required mounting location and secure using four countersunk screws. Make sure that the heads of the screws do not protrude.
 5. Place the sensor module in the housing.
 6. Slide the clamping element flush into the housing. Check that the sensor element is seated correctly.
 7. Finally tighten the central screw.
- The sensor is now mounted correctly.

Baud rate setting

Inclination sensors by Pepperl+Fuchs are supplied with a baud rate of 250 kbit/s. To change the baud rate, write the new baud rate to object 2001h "Baud rate." If a "Reset sensor" command is issued via an NMT message or the power supply is interrupted, the sensor operates at the new baud rate. Invalid values are not adopted. In this case, the current setting is retained.

Example of modifying the baud rate from 250 kbit/s to 1 Mbit/s:

| | | | | | | | | |
|--------|-------------|--------------|-------------|---------------|-------------|-------------|-------------|-------------|
| 601h | 2Fh | 01h | 20h | 00h | 08h | xxh | xxh | xxh |
| CAN-ID | Com-mand | Object index | Subindex | New baud rate | not used | | | |
| | Data byte 1 | Data byte 2 | Data byte 3 | Data byte 4 | Data byte 5 | Data byte 6 | Data byte 7 | Data byte 8 |

CAN ID: 601h, SDO1 channel of node 1

Command: 2Fh, write object, 1 byte of usable data

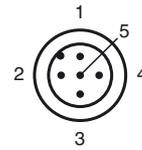
Object index: 2001h, note: low byte first, then high byte!

Subindex: 00h

New baud rate: 08h, for 1 Mbit/s

New baud rate: 07h, for 800 kbit/s

Pinout



Wire colors in accordance with EN 60947-5-2

- | | | |
|---|----|---------|
| 1 | BN | (brown) |
| 2 | WH | (white) |
| 3 | BU | (blue) |
| 4 | BK | (black) |
| 5 | GY | (gray) |

Accessories

V15-G-2M-PUR-CAN-V15-G

DeviceNet/CANOpen bus cable, M12 to M12, PUR cable 5-pin

V15-G-5M-PUR-CAN-V15-G

DeviceNet/CANOpen bus cable, M12 to M12, PUR cable 5-pin

V15-G-10M-PUR-CAN-V15-G

DeviceNet/CANOpen bus cable, M12 to M12, PUR cable 5-pin

V15S-T-CAN/DN-V15

Y distributor, M12 socket on M12 connector/socket

ICZ-TR-CAN/DN-V15

Terminal resistor for DeviceNet, CANOpen

New baud rate: 06h, for 500 kbit/s
New baud rate: 05h, for 250 kbit/s
New baud rate: 04h, for 125 kbit/s
New baud rate: 03h, for 100 kbit/s
New baud rate: 02h, for 50 kbit/s
New baud rate: 01h, for 20 kbit/s
New baud rate: 00h, for 10 kbit/s

LED displays

The inclination sensor has three indicator LEDs that allow rapid visual monitoring.

- The green **power** LED indicates the state of the power supply
- The yellow **run** LED indicates the bus and sensor status
- The red **err** LED indicates an error

| power (green) | run (yellow) | err (red) | Meaning |
|---------------------|-------------------------|-------------|--|
| Off | Off | Off | No power supply |
| On | Flashing constantly | Off | Pre-operational |
| On | 1x flashing | Off | Stopped |
| On | On | Off | Operational |
| On | Off | On | CAN bus off |
| On | depending on bus status | 1x flashing | Warning, e.g., outside measuring range |
| On | depending on bus status | 2x flashing | Error, e.g., EEPROM checksum incorrect |
| Flashing constantly | Off | On | Undervoltage |