Indoor, Duct & Wall mounting type Temperature/Humidity transducer



Specifications

Model		THD-R-PT	THD-R-PT/C	THD-R-C THD-R-V THD-R-T	THD-D THD-W	THD-DD - THD-WD -
Display type		—	Non-indicating type	Non-indicating type		
Display digit —		—			Each 3digits for temp./humidity	
Character size —			—			W6.2×H10.0mm
Power supply		—	24VDC			
Allowable volta	age range	90 to 110% of rated ve	oltage			
Power consum	ption	—	Max. 2.4W			
Measuring inpu	ut	Temperature (Built-in sensor)	Temperature, Humidity	y(Built-in sensor)		
Temp. DPt10		DPt100Ω resistance v	alue DC4-20mA, 1-5VDC,			
Output ^{×1}	Humidity	—	DC4-20mA RS485 communication output(Modbus R)
Measurement	Temp.	-19.9 to 60.0°C				
range	Humidity	—	0.0 to 99.9%RH(THD-R is required to attend for using over 90%RH.)			
	Temp.	Max. ±0.8°C	-19.9 to 5.0°C: ±1.0°C rdg ±1digit (At below -			2
Accuracy	Humidity		Max. ±3%RH at 30 to (at 25 to 45°C)	9 8 7 6 70%RH 5 4 3 2 2	$0 - \pm 5.0$ $0 - \pm 4.0$ $0 - \pm 3.0$ $0 - \pm 4.0$ $0 - \pm 3.0$ $0 - \pm 4.0$ $0 - \pm 5.0$ $0 - \pm 4.0$	6RH 6RH 6RH 6RH 6RH 6RH 6RH 6RH 6RH 6RH
Sampling cycle	9	—	Fixed in 0.5 sec.			

 \times 1. The allowable impedance of current output is max. 600 Ω

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Temperature/Humidity Transducer

Specifications

							Photo	
Model		THD-R-PT	THD-R-PT/C	THD-R-C THD-R-V THD-R-T	THD-D	THD-DD	(B) Fiber	
Insulation resistance —		Min. 100MΩ(at 500	Min. 100MΩ(at 500VDC megger)					
Dielectric strength		500VAC 50/60Hz fe	or 1 minute			7		
Noise res	sistance	—	±0.3kV the square	wave noise(pulse width:1µ	s) by the noise simulator		(C) Door/Area sensor	
\/:h	Mechanical	—	0.75mm amplitude	mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 1hour				
Vibration	Malfunction	—	0.5mm amplitude a	5mm amplitude at frequency of 10 to 55Hz(for 1 min.) in each of X, Y, Z directions for 10min.				
Ohaala	Mechanical	_	300m/s²(approx. 30	00m/s²(approx. 30G) in each of X, Y, Z directions for 3 times				
Shock	Malfunction	—	100m/s²(approx. 10	00m/s ² (approx. 10G) in each of X, Y, Z directions for 3 times				
Protection IP10		<u>.</u>		IP65(except sensing	part)	(E) Pressure sensor		
Ambient	temperature	-20 to 60°C, sto	rage: -20 to 60°C				1	
Cable Terminal type				4-wire, ø4, Length: 2	2m	(F) Rotary		
Approval		CE					encoder	
Unit weig	ght	Approx. 55g			Approx. 160g		(G)	
× Enviro	nment resista	ance is rated at n	o freezing or condens	sation.			Connector/ Socket	

Dimensions





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(U) Other

(A) Rhoto

THD Series



THD-R-PT



*Check terminal connection diagram and wire the power supply part carefully.

O THD-D / THD-W



Case detachment

• THD-R

Unfasten the bolt on the bottom of the product, separate the case from it.



THD-D / THD-W

Unfasten 4 bolts on the top of the product, separate the case cover from it.



Functions

O Voltage output

It transmits current temperature/humidity to other devices (PC, recorder, etc.) and outputs 1-5VDC. It outputs 1VDC at -19.9°C of temperature and 0%RH of humidity, 5VDC at 60°C of temperature and 99.9%RH of humidity. The temperature and humidity output are separated and the resolution is divisible by 1,000.

O Current output

It transmits current temperature/humidity to other devices (PC, recorder, etc.) and outputs DC4-20mA. It outputs DC4mA at -19.9°C of temperature and 0%RH of humidity, DC20mA at 60°C of temperature and 99.9%RH of humidity. The temperature and humidity output are separated and the resolution is divisible by 1,000.

© Temperature sensor output(DPt 100Ω resistance value output)

It transmits current temperature to other devices (recorder, thermometer, etc.). It outputs 100Ω at 0°C and 119.40Ω at 50°C. (TCR=3850 ppm/°C)

RS485 communication output

It is output transmit current temperature and humidity to other devices by communication.

Interface

Standard	EIA RS485
Maximum connections	31(Address setting: 01 to 31)
Communication method	2-wire half duplex
Synchronous method	Asynchronous
Effective communication distance	Max. 800m
Communication speed	1200 to 115200bps(Setting)
Start bit	1bit(Fixed)
Stop bit	1bit(Fixed)
Parity bit	None(Fixed)
Data bit	8bit(Fixed)
Protocol	Modbus RTU

※It is not possible to change parameter related to communication of THD under the communication with high order system.
※Match the parameter of THD communication to be same as the high order system.

XIt is not allowed to set overlapping communication address at the same communication line.

*Please use a proper twist pair for RS485 communication.

O Application of system organization



XIt is recommended to use communication converter, RS232C to RS485 converter(SCM-38I, sold separately), USB to RS485 converter(SCM-US48I, sold separately).

◎ Ordering of communication control

- The communication method is Modbus RTU.
- After 0.5sec. being supplied the power into master system, it is able to start communication.
- The initial communication is started by master system. When a command comes out from the master system, THD will respond.

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(A) Photo electric sensor

(B) Fiber optic senso

(C) Door/Area sensor (D) Proximity

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controll

(I) SSR/

Power controller

(J) Counter

(K) Timer

(L) Panel meter

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode pow supply

(Q) Stepper motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

Communication command and block

The format of query and response.

Query

Address code	Command	Start address	Number of data	CRC16			
Calculation range of CRC16							

①Address code: This address code is for identifying THD by master system and able to set within range of 01 to 31.
 ②Command: Read command for input register

③Start address: The start address of input register to read (Start address). It is available to select 0000 and 0001 for start address. 16bit data in the address 0000 indicates temperature value, 16bit data in the address 0001 indicates humidity value. (Refer to Modbus Mapping table.)

④Number of data: The number of 16bit data from start address (No. of Points). When start address is 0000, it is available to read 2 of 16 bit data, or when start address is 0001, it is available to read 1 of 16 bit data.

⑤CRC16: Checksum for checking the whole frame and it is used for more reliable transmit/receive to check the error between transmitter and receiver.

Response

Address code	Command	Number of data	Temperature data	Humidity data	CRC16		
Calculation range of CRC16							

①Address code: This address code is for identifying THD by master system and able to set within range of 01 to 31. ②Command: A response for read command of input register

③Number of data: The number of 8 bit data to send from start address (No. of bytes). When start address is 0000, it is available to read 4 of 8 bit data, or when start address is 0001, it is available to read 2 of 8 bit data. (Refer to Modbus Mapping table.)

④Temperature data: This is the value of 16bit. To get a current temperature value, divide read value by 100. Ex)When read data is 0x09B6, decimal value is 2486, the current value is 2486/100=24.86jÉ.

(5) Humidity data: This is the value of 16bit. To get a current humidity value, divide read value by 100.

Ex)When read data is 0x12FE, decimal value is 4862, the current value is 4862/100=48.62%RH.

©CRC16: Checksum for checking the whole frame. (Refer to L-35 page for CRC16 Table.)

• Application for communication command

(Query): Address code(01), Start address(0000), The number of 16 bit data to read(2) CRC16(0x71CB)

01	04	00	00	00	02	71	СВ
Address code	Command	Start address		Amount of data		CRC16	
		High	Low	High	Low	High	Low

(Response): Address code(01), The number of 8 Bit data to read(4), Temperature(0x09B6), Humidity(0x12FE) CRC(0x94DE)

01	04	04	09	B6	12	FE	94	DE
Address	Response	Amount	Temperature da	ata	Humidity data		CRC16	
code	command	of data	High	Low	High	Low	High	Low

● Error processing(Slave → Master)

1. Not supported command

01	81	01	81	90
Address code	Response command	Exception code	CRC16	

*Set a received highest bit and send it to response command and exception code 01.

2. The start address of queried data is inconsistent with the transmittable address.

01	81	02	81	90
Address code	Response command	Exception code	CRC16	

XSet a received highest bit and send it to response command and exception code 02.

3. The number of queried data is bigger than transmittable one.

01	84	03	Х	Х
Address code	Response command	Exception code	CRC16	

XSet a received highest bit and send it to response command and exception code 03.

4. Abnormal operation for a received command

01	84	04	X	Х
Address code	Response command	Exception code	CRC16	

XSet a received highest bit and send it to response command and exception code 04.



Temperature/Humidity Transducer

Communication

Setting communication speed

- 1) Set SW1 to 0 and apply the power.
- 2) Operation indicator LED is flashing.
- 3) Set a communication speed after choose SW1 within the range 1 to 8 and holdit for 3sec.
- 4) After setting a communication speed, the LED will be ON. At the moment turn OFF the power.
- ※Factory default communication speed is 9600bps.
- XIn order to change the communication speed, please turn off the power and repeat step 1 to 4.

O Change the communication address

- 1) Set CAL terminal and SW1 at new address, apply the power.
- 2) The communication address is changed automatically.
- ※Factory default communication address is 01. (SW1: 1, CAL terminal: Open)
- ※In order to change the communication address, please turn off the power and repeat step 1) to 2).

Setting table of communication address

CAL terminal	SW1	Add no.	CAL terminal	SW1	Add no.
OPEN	1	01	SHORT	0	16
OPEN	2	02	SHORT	1	17
OPEN	3	03	SHORT	2	18
OPEN	4	04	SHORT	3	19
OPEN	5	05	SHORT	4	20
OPEN	6	06	SHORT	5	21
OPEN	7	07	SHORT	6	22
OPEN	8	08	SHORT	7	23
OPEN	9	09	SHORT	8	24
OPEN	A	10	SHORT	9	25
OPEN	В	11	SHORT	A	26
OPEN	С	12	SHORT	В	27
OPEN	D	13	SHORT	С	28
OPEN	E	14	SHORT	D	29
OPEN	F	15	SHORT	E	30
<u> </u>	—		SHORT	F	31

O Modbus Mapping Table

Caution for using

connect the wires correctly.

Address	Item	Remark
30001(0000)	Temperature value	Temperature value × 0.01
30002(0001)	Humidity value	Humidity value × 0.01

XVisit our website(www.autonics.com) to download monitoring program for RS485 communication output.



<Setting table for communication speed(bps)>

(C) Door/Area (D) Proximity

(A) Photo electric

sensor

(B) Fiber optic senso

(E) Pressure

(F) Rotary encode

(G) Connector Socket



Operation

indicator

(I) SSR/ Power controlle

(K) Timer

(L) Panel mete

(M) Tacho/ Speed/ Pulse meter

(N) Display unit

(O) Sensor controller

(P) Switching mode powe supply

(Q) Stepper

motor& Driver&Co

(R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

- Do not touch the temperature/humidity sensor by hands. • This unit must be mounted on the wall. (THD-R)
- Caution for cleaning

power is applying.

- · Use dry towel.
- · Do not use acid, chrome acid, solvent but alcohol.

After checking the input specification, terminal polarity,

Do not connect a wire, examine and repair when the

- Turn off the power before cleaning the unit. After 30min. of cleaning, supply the power to the unit.
- · Do not inflow dust or wire dregs into the unit.

- The connection wire of this unit should be separated from the power line and high voltage line in order to prevent from inductive noise.
- Keep away from the high frequency instruments.(High frequency welding machine & sewing machine, big capacitive SCR controller)
- The switch or circuit-breaker should be installed near by users.
- Installation environment
 - It shall be used indoor.
 - Altitude Max. 2000m.
 - Pollution Degree 2
 - Installation Category II.
- Autonics



<Inner PCB of THD-D/THD-W>

switch to set address and communication speed.

×1. Only when communication setting, remove the case cover and adjust the communication setting

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