## Single phase, Analog input type SSR

### Features

- Power control/ Cycle control/Phase control (fixed cycle/ variable cycle) are available with 4-20mA analog input
- Superior dielectric strength : 4,000VAC
- Improved reliability by maximizing heat protection efficiency with heatsink integrated design and ceramic board
- Various mounting methods (DIN rail, panel front)
- Checks input status by Input LED(green)



NEW

Please read "Caution for your safety" in operation manual before using.



#### Ordering information SRP 30 2 н Rated load current 20 20A (resistive load) 30 30A 60 60A 2 100-240VAC Load voltage(rated) 4 200-480VAC Input voltage(rated) A 4-20mA analog input Control phase 1 Single phase Туре Н Integrated heatsink type SSR Item Analog input type (proportional control) SRP no-power SSR

Model	Rated load current	Load voltage
SRPH1-A220	20A	
SRPH1-A230	30A	100-240VAC
SRPH1-A260	60A	1

Model	Rated load current	Load voltage
SRPH1-A420	20A	
SRPH1-A430	30A	100-240VAC
SRPH1-A460	60A	

## Specifications

#### O Input

4-20mA analog input	
Max. allowable input current	50mA
Pick-up current	4.2mA
Static off current	0.2mA
Power factor	Min. 0.9 (max. 25° of difference between voltage phase and current phase)
Input LED	Green
Start-up time	60Hz: 200ms, 50Hz: 250ms
Operation time	60Hz: 16.6ms, 50Hz:20ms
Operation mode <sup>**1</sup>	Cycle control(fixed cycle, variable cycle) Phase control(phase equality division type, power equality division type)

%1: You can change operation mode by jumper pin. Default is Phase control(Power equality division type).

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# Analog Input Type SSR

Spece	cifications
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Spec	cifications	3			(A) Photo
Outpu	ıt				electric sensor
100-240VAC load voltage				(B) Fiber optic sensor	
Load voltage	e range(50/60Hz)	90-264VACrms(50/60Hz)			Sensor
Rated load current Ta=25°C	Resistive load (AC-51)	20Arms	30Arms	60Arms	(C) Door/Area sensor
Min. load cu	l current 0.5Arms			(D) Proximity	
Max. 1 cycle (60Hz)	e surge current	300A	500A	1000A	sensor
Max. non-re current(l <sup>2</sup> t, t	petitive surge =8.3ms)	350A <sup>2</sup> S	1000A <sup>2</sup> S	4000A <sup>2</sup> S	(E) Pressure sensor
Peak voltag	e(Non-repetitive)	600V			(F)
Leakage current (240VAC/60Hz, Ta=25°C) Max. 10mArms			Rotary encoder		
Output ON voltage drop[Vpk] (max. load current) Max. 1.6V			(G) Connector/ Socket		
Static off sta	ate dv/dt	500V/µs			
	C load voltage	1			(H) Temp. controller
Load voltage	range(50/60Hz)	200-528VACrms			
Rated load current	Resistive load (AC-51)	20Arms	30Arms	60Arms	(I) SSR/ Power controller
Ta=25°C	Motor load (AC-53a)	5Arms	8Arms	15Arms	(L)
Min. load cu	irrent	0.5Arms			Counter
Max. 1 cycle (60Hz)	e surge current	300A	500A	1000A	(K) Timer
Max. non-re current(l <sup>2</sup> t, t	petitive surge =8.3ms)	350A <sup>2</sup> S	1000A <sup>2</sup> S	4000A <sup>2</sup> S	
Peak voltage(non-repetitive) 1000V			(L) Panel		
Leakage cu (480VAC/60	rrent Hz, Ta=25°C)	Max. 10mArms			(M)
Output ON [Vpk](Max. I	voltage drop oad current)	Max. 1.6V			Tacho/ Speed/ Pulse meter
Static off sta	ate dv/dt	500V/µs			(N)
					Display unit

#### **O General Specifications**

Certification UL508, CSA22.2, No.14, IEC/EN 60947-4-3		(O) Sensor	
Phase cor	ntrol	5 to 99%	controller
(phase equality division type)			(P) Switching
Phase control (power equality division type)		10 to 99%	mode power supply
Frequency reading function		Yes	(Q) Stepper
Dielectric strength(Vrms)		4000VAC 50/60Hz for 1min. (Input-Output, Input/Output-Case)	motor& Driver&Controller
Insulation resistance		Min. 100MΩ(at 500VDC megger)	(R)
Vibration		10 to 55Hz double amplitude 0.75mm in each of X, Y, Z directions for 1 hour	Graphic/ Logic
Environ -ment	Ambient temperature	-20 to 70°C, storage : -20 to 100°C (The rated load current capacity is different depending on ambient temperature. Refer to <sup>™</sup> SSR Derating curve'.)	(S) Field
	Ambient humidity	45 to 85%RH	device
Input terminal connection		Min. 1×0.5mm <sup>2</sup> (1×AWG20) Max. 1×1.5mm <sup>2</sup> (1×AWG6) or Max. 2×1.5mm <sup>2</sup> (2×AWG16)	
Output ter	minal connection	Min. 1×1.5mm <sup>2</sup> (1×AWG16) Max.1×16mm <sup>2</sup> (1×AWG6) or Max. 2×6mm <sup>2</sup> (2×AWG10) %Connect appropriate cable for the load current capacity to output terminal.	(T) Software
Input terminal fixed torque		0.75 to 0.95N·m	(U)
Output terminal fixed torque		1.6 to 2.2N·m	Other
Unit weight		• SRPH1-A220, SRPH1-A230, SRPH1-A420, SRPH1-A430 : Approx. 410g • SRPH1-A260, SRPH1-A460 : Approx. 680g	

% For wiring the terminal, an O-ring terminal must be used.

\*Environment resistance is rated at no freezing or condensation.

### Dimensions & Mounting

#### $\ensuremath{\mathbb{O}}$ Dimensions





#### (unit: mm)

#### O Hole cut-out for panel front mounting



※Tightening torque for mounting: 1.8 to 2.5N⋅m







Panel

Installation interval

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100

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%For mounting multiple SSR, please keep certain installation intervals for heat prevention. For horizontal installation (when the heights of input part and output part are equal), it is recommended to apply 50% of rated load current.

#### High temperature caution Make sure do not touch the heat sink or the unit body while power is supplied or right after load power is turned off. If not, it may cause a burn.

#### **Autonics**

## Analog Input Type SSR



### Operation mode

- **O** Phase control
- Output waveform of phase control
  - When control input signal is 25% When control input signal is 50% When control input signal is 75%



※1: The black parts of output waveform are output on the load.





Controls output power which is proportional to control input(4-20mA) level.

#### ○ Cycle control

#### • Fixed cycle

Controls continuously the number of full cycle which is supplied to load every 1sec. by being proportional to control input (4-20mA).



#### Variable cycle

Controls fast and accurately the subject with optimized the number of AC voltage cycle which is supplied to load by being proportional to control input (4-20mA).

- When control input signal is 10%
- When control input signal is 50%





#### • Phase equality division type



Controls phase angle which is proportional control input(4-20mA) level.

# Analog Input Type SSR

(A) Photo electric

(B) Fiber optic sensor

(C) Door/Area sensor

(D) Proximity

(E) Pressure

(F) Rotary encoder

(G) Connector/ Socket

(H) Temp. controlle

(I) SSR/

(J) Counter

(K) Timer

(L) Panel

mete

(M) Tacho/ Speed/ Pulse meter (N) Display unit

(O) Sensor controller

(P) Switching mode powe supply (Q) Stepper motor& Driver&Contr (R) Graphic/ Logic panel

(S) Field network device

(T) Software

(U) Other

### Proper usage

#### A High temperature caution

Make sure do not touch the heat sink or the unit body while power is supplied or right after load power is turned off. If not, it may cause a burn.

#### A Caution for using

- 1. Attach a heatsink and ventilate for smooth convection current. If not, congested heat transfer may cause product failure or malfunction.
- 2. For mounting multiple SSR, please keep certain installation intervals for heat prevention. For horizontal installation (when the heights of input part and output part are equal), it is recommended to apply less than 50% of the rated load current.
- 3. Make sure do not touch the heatsink or the unit body while power is supplied or right after load power is turned OFF.
- If not, it may cause a burn.
- 4. Connect the proper cable for the rated load current with output terminal.
- 5. Use rapid fuse of which I<sup>2</sup>t is under 1/2 of SSR I<sup>2</sup>t in order to protect the unit from load's short- circuit current.
- 6. In case of a short-circuit please replace the fuse with a 1/2 of SSR  $l^2t$  value specified semiconductor protective type.
- 7. In case that load's current is lower than SSR min. load current, connect dummy resistance to the load in parallel so as to make load's current higher than SSR min. load current.
- 8. Make sure that the screw on output terminal is tightly fastened. Using the unit with loose bolt may cause product failure or malfunction.
- 9. Do not touch the load's terminal even if output is OFF. It may cause electric shock.
- 10. The input of the 4-20mA should be supplied by the insulated and limited voltage/current or by class 2 power supply.

**Autonics** 

- 11. Proper application environment (Avoid following environments to install)
- ① Where temperature/humidity is beyond the specification
- ② Where dew condensation occurs due to temperature change
- ③ Where inflammable or corrosive gas exists
- Where direct rays of light exist
- 6 Where severe shock, vibration or dust exists
- 6 Where near facilities generating strong magnetic forces or electric noise
- 12. Installation environment
- ① It shall be used indoor
- ② Altitude Max. 2,000m
- ③ Pollution Degree 2
- ④ Installation Category III